

FIG. 1A

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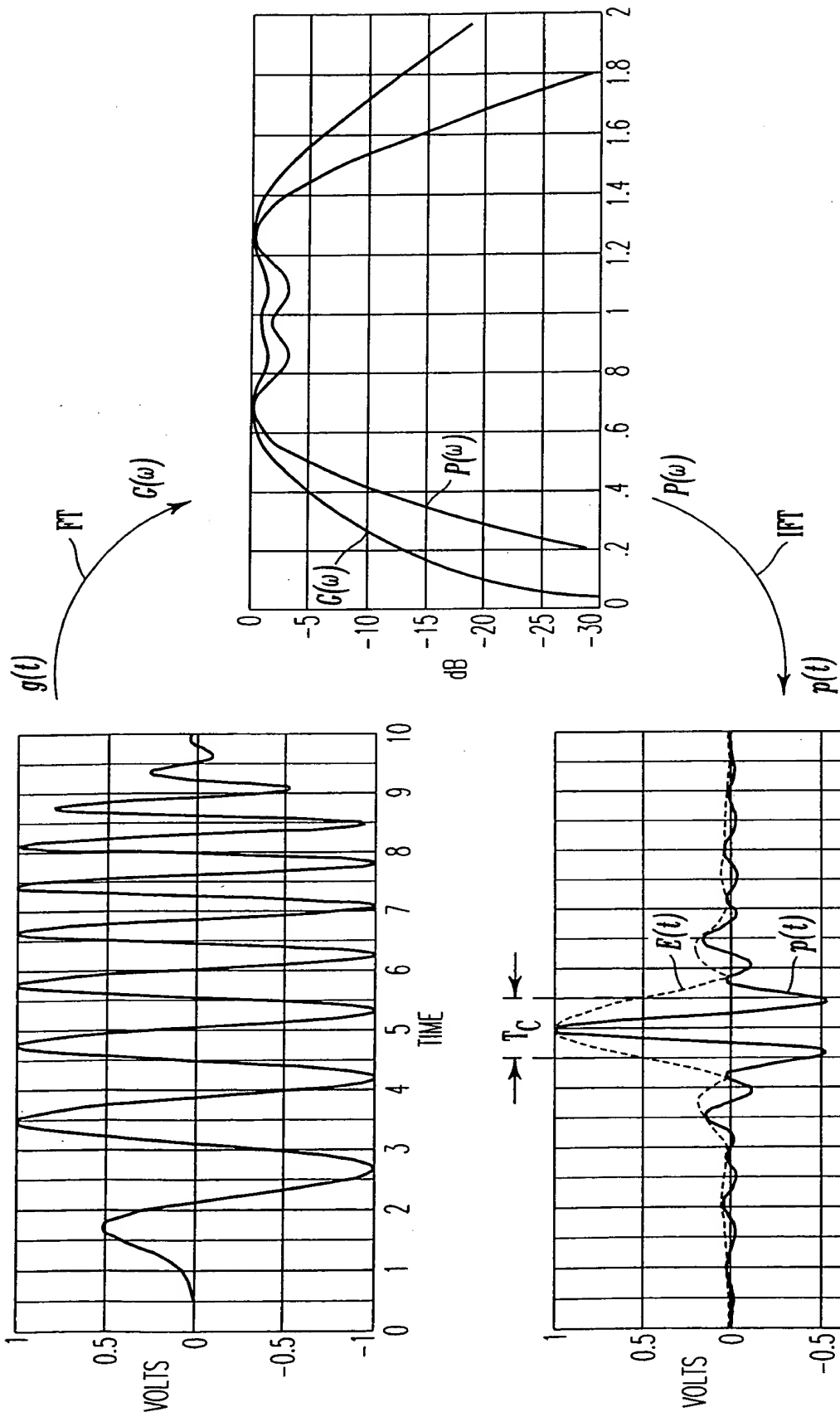


FIG. 1B

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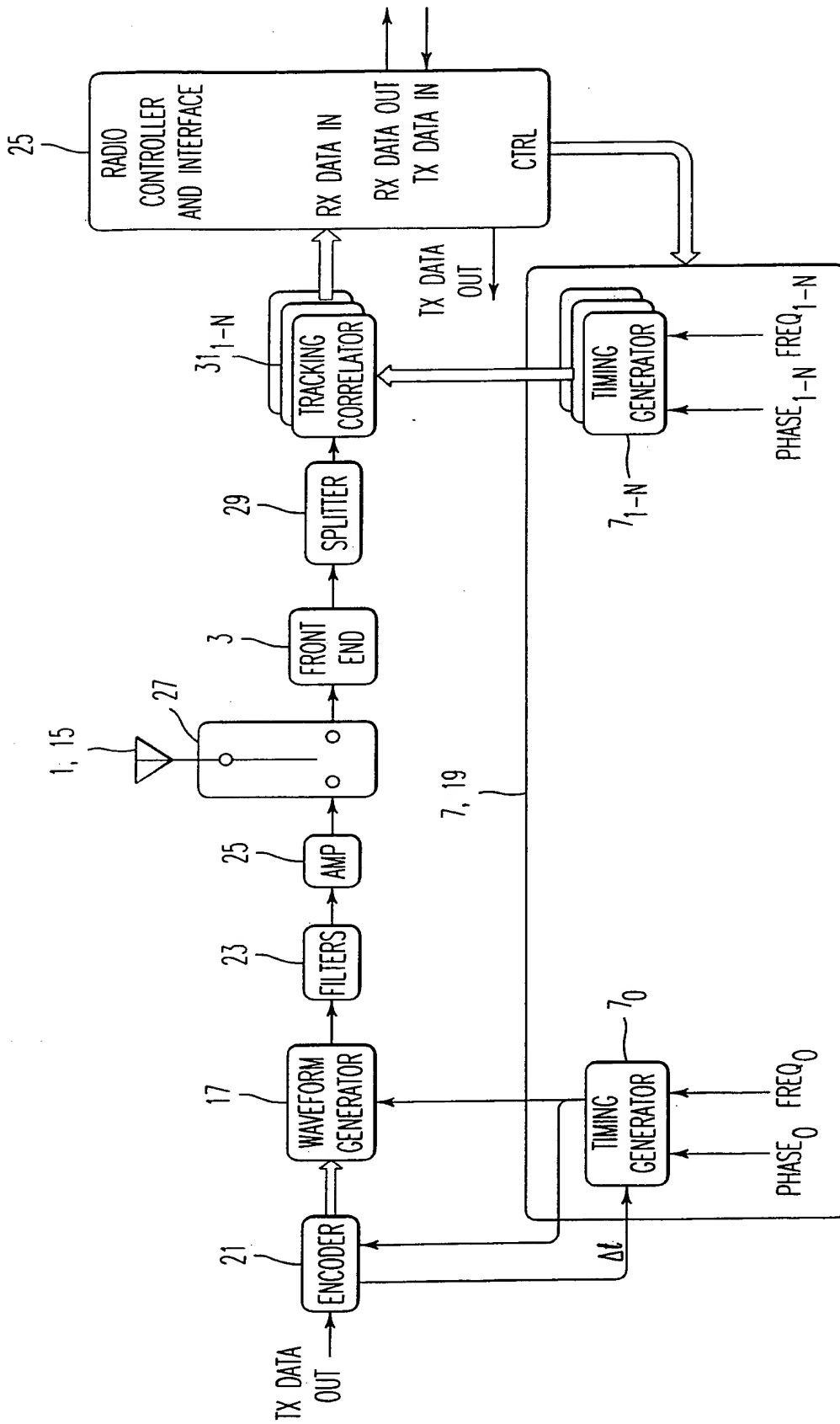
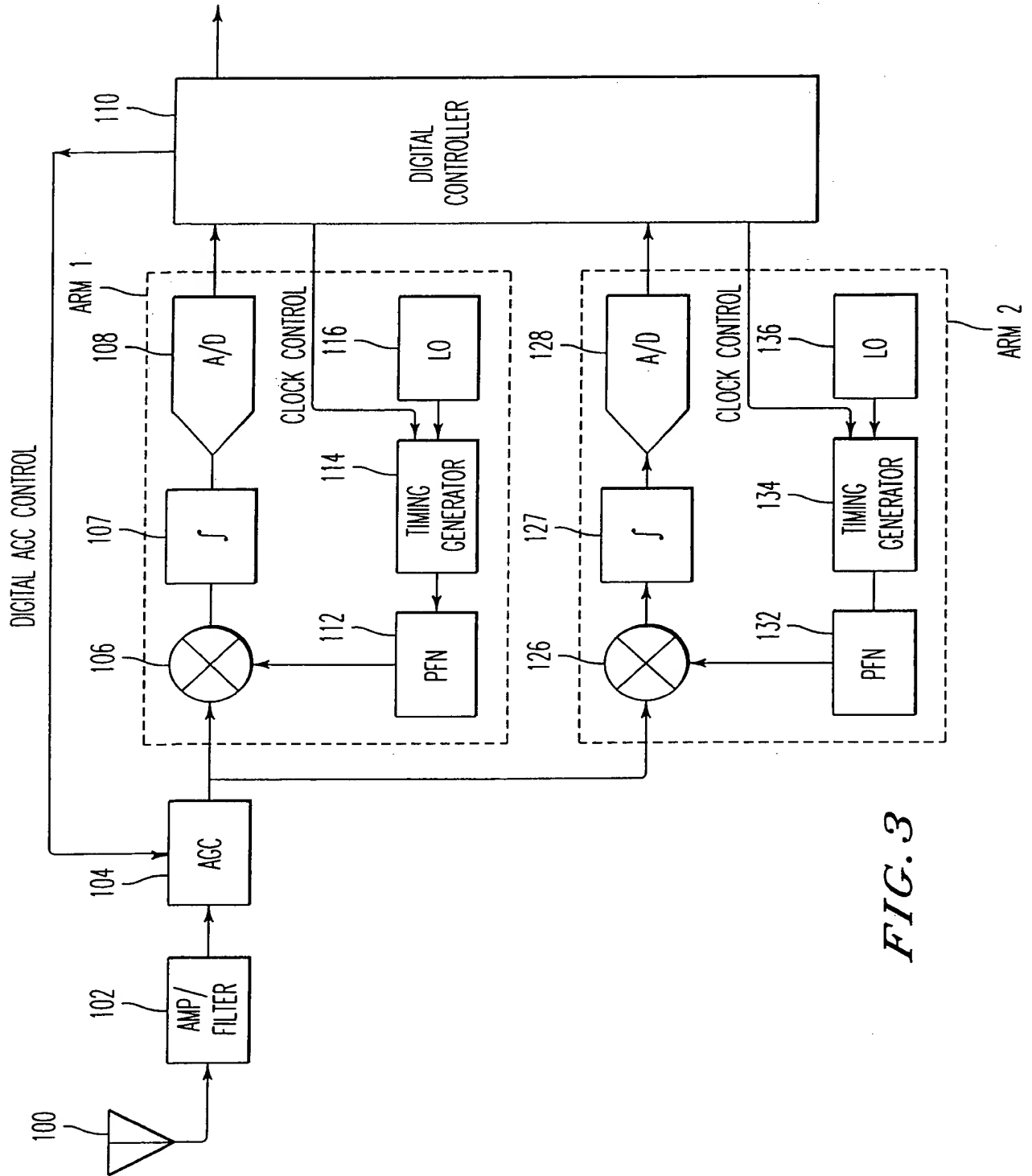
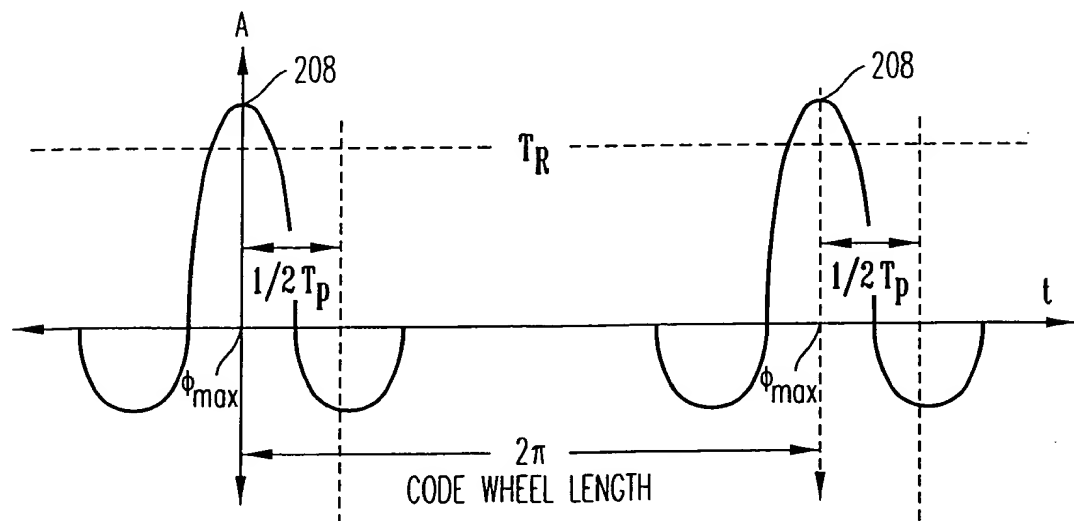
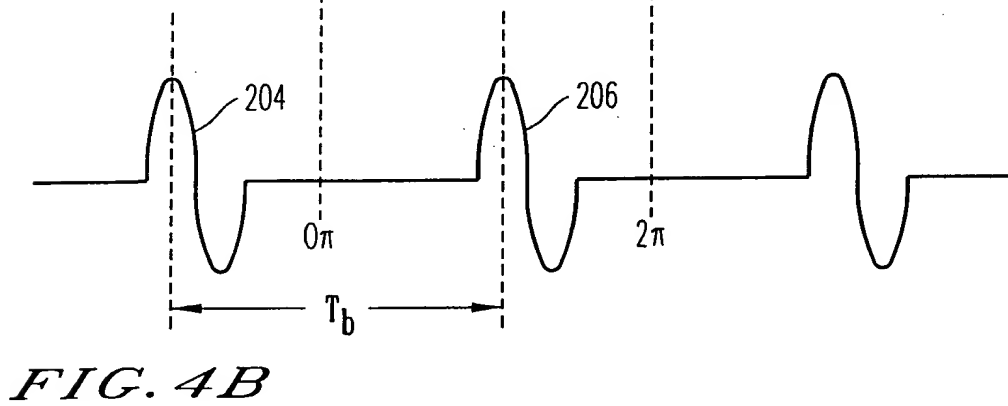
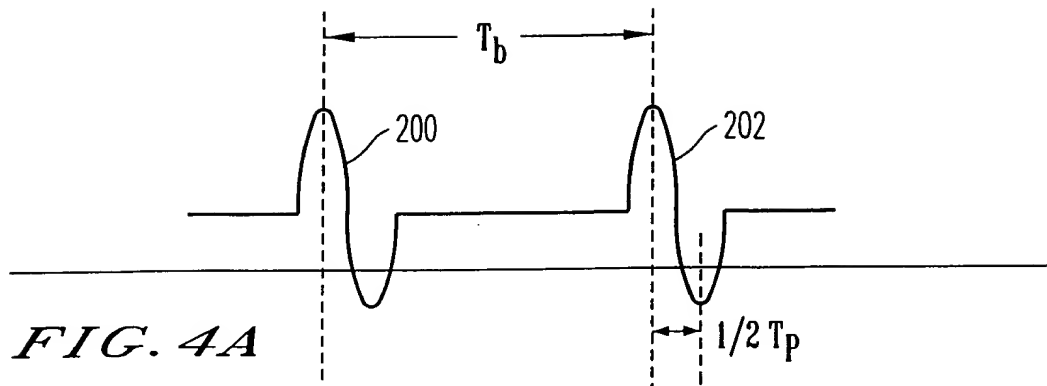


FIG. 2

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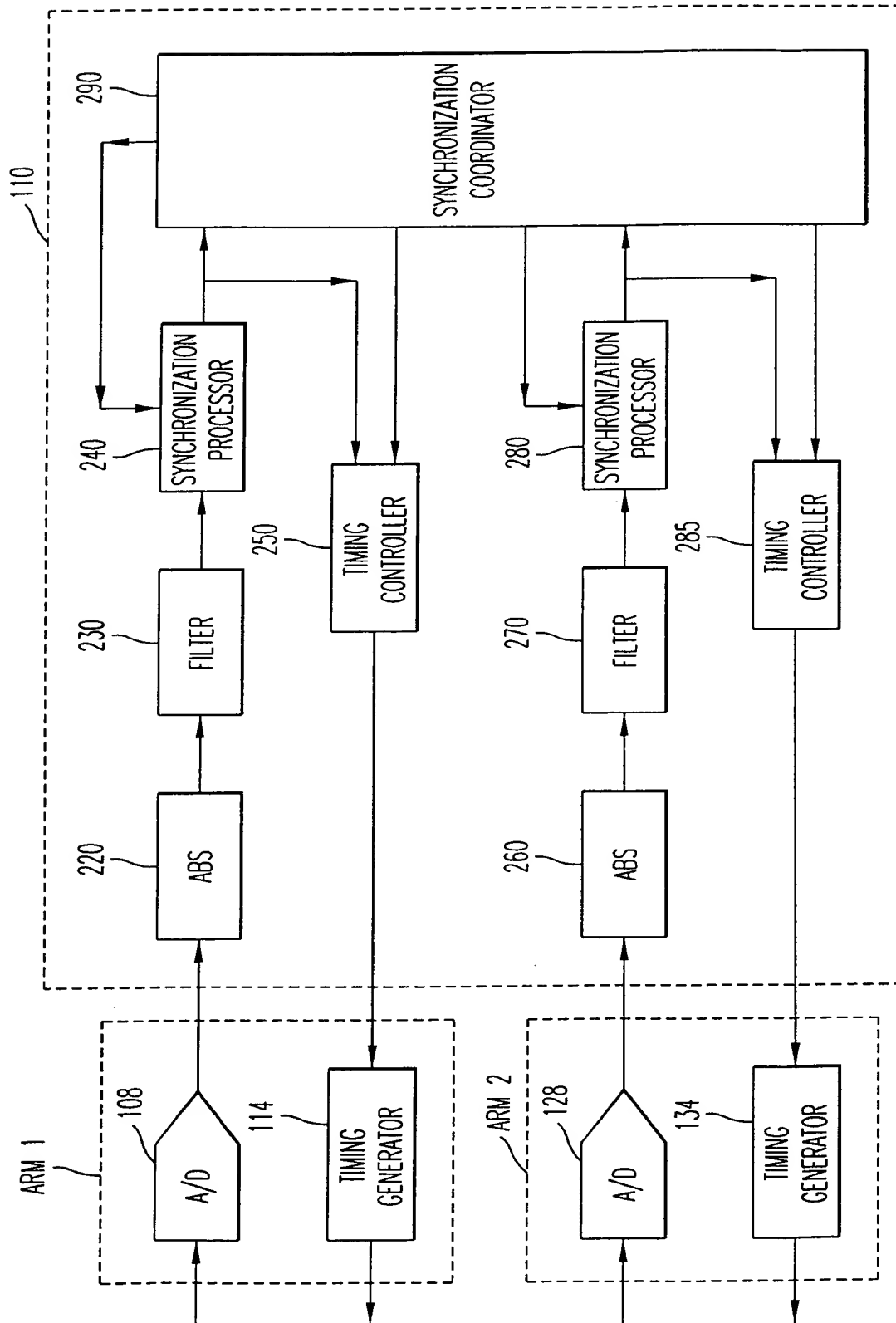
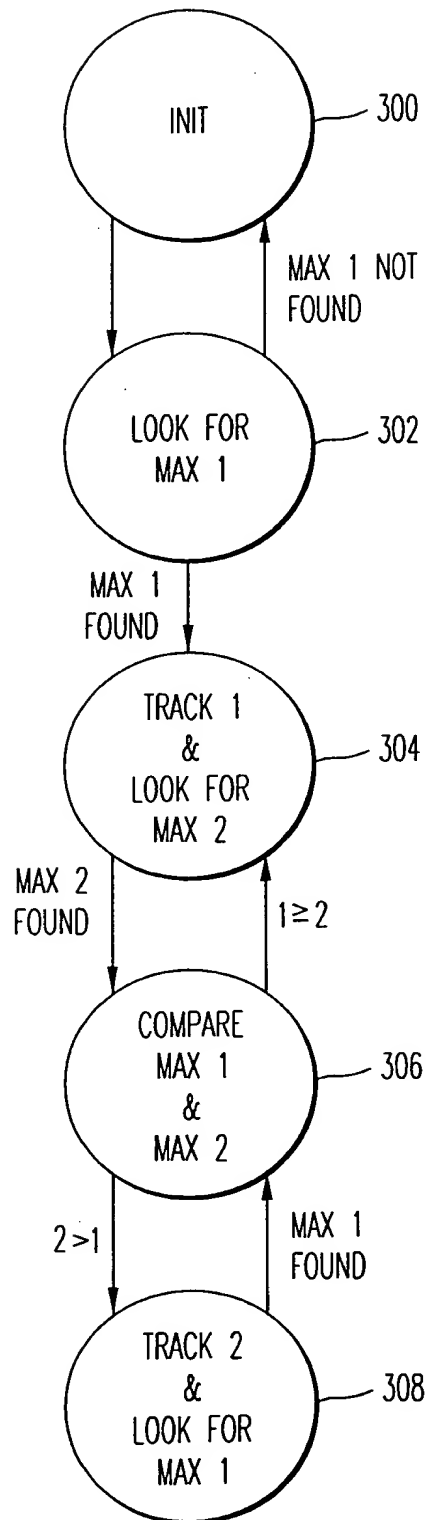


FIG. 4D

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*FIG. 5*

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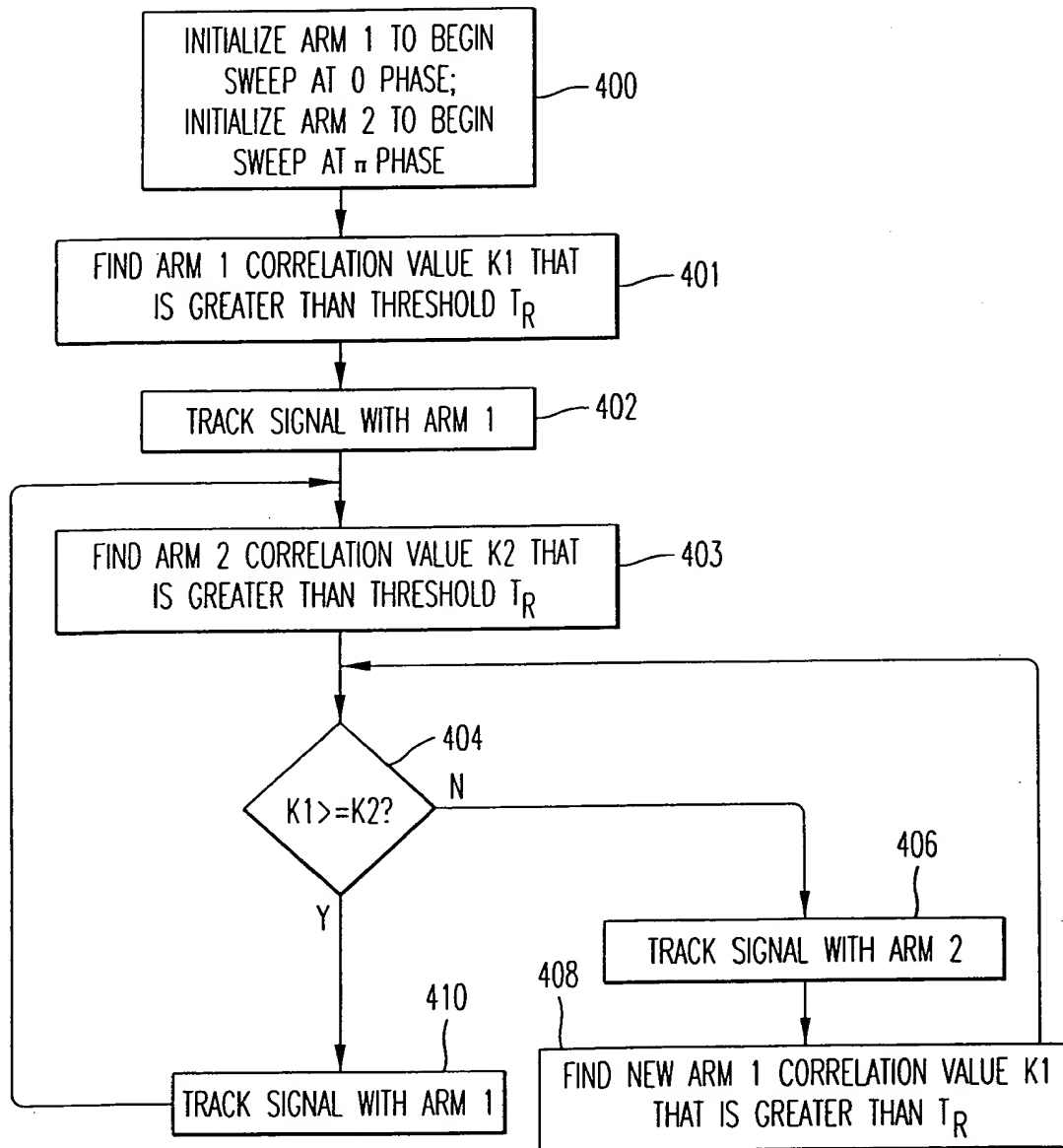
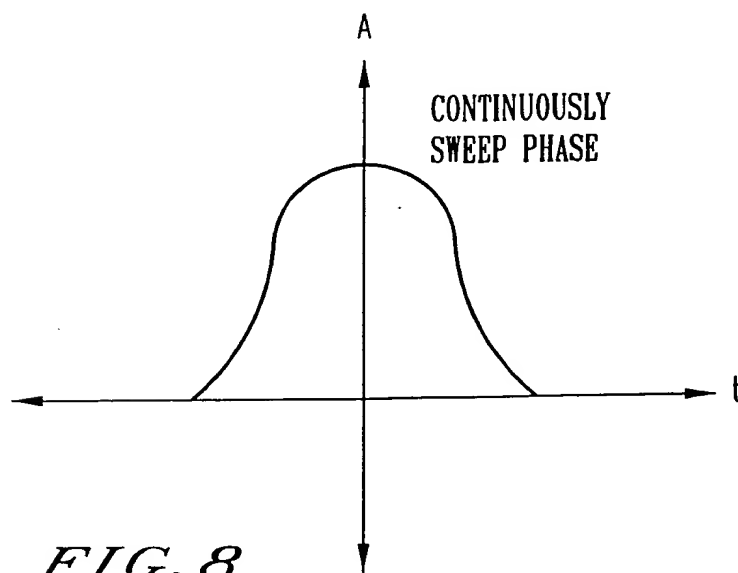
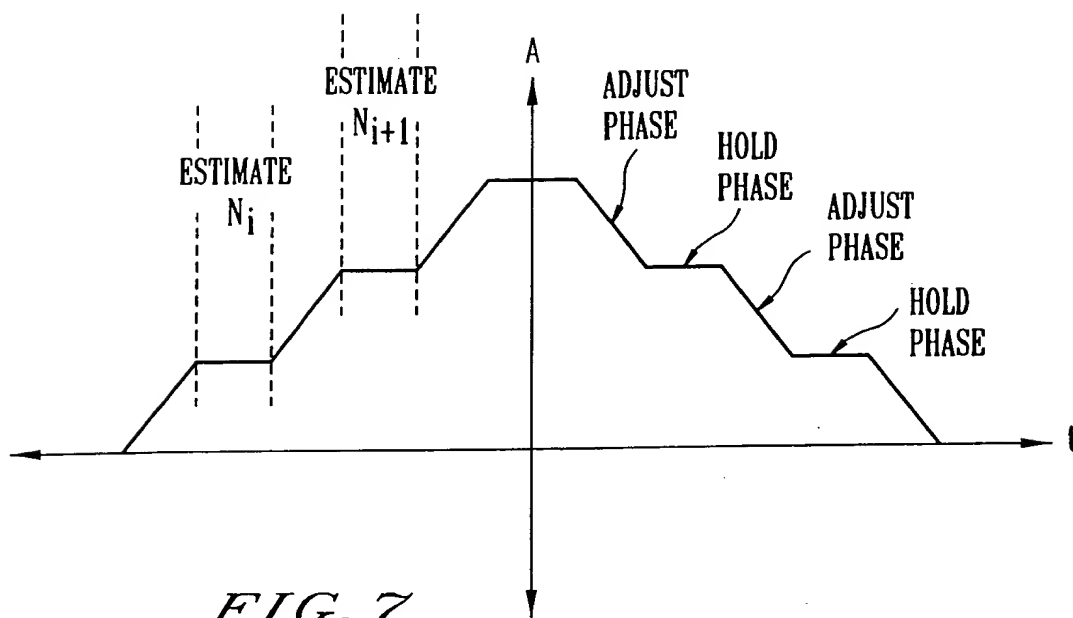


FIG. 6

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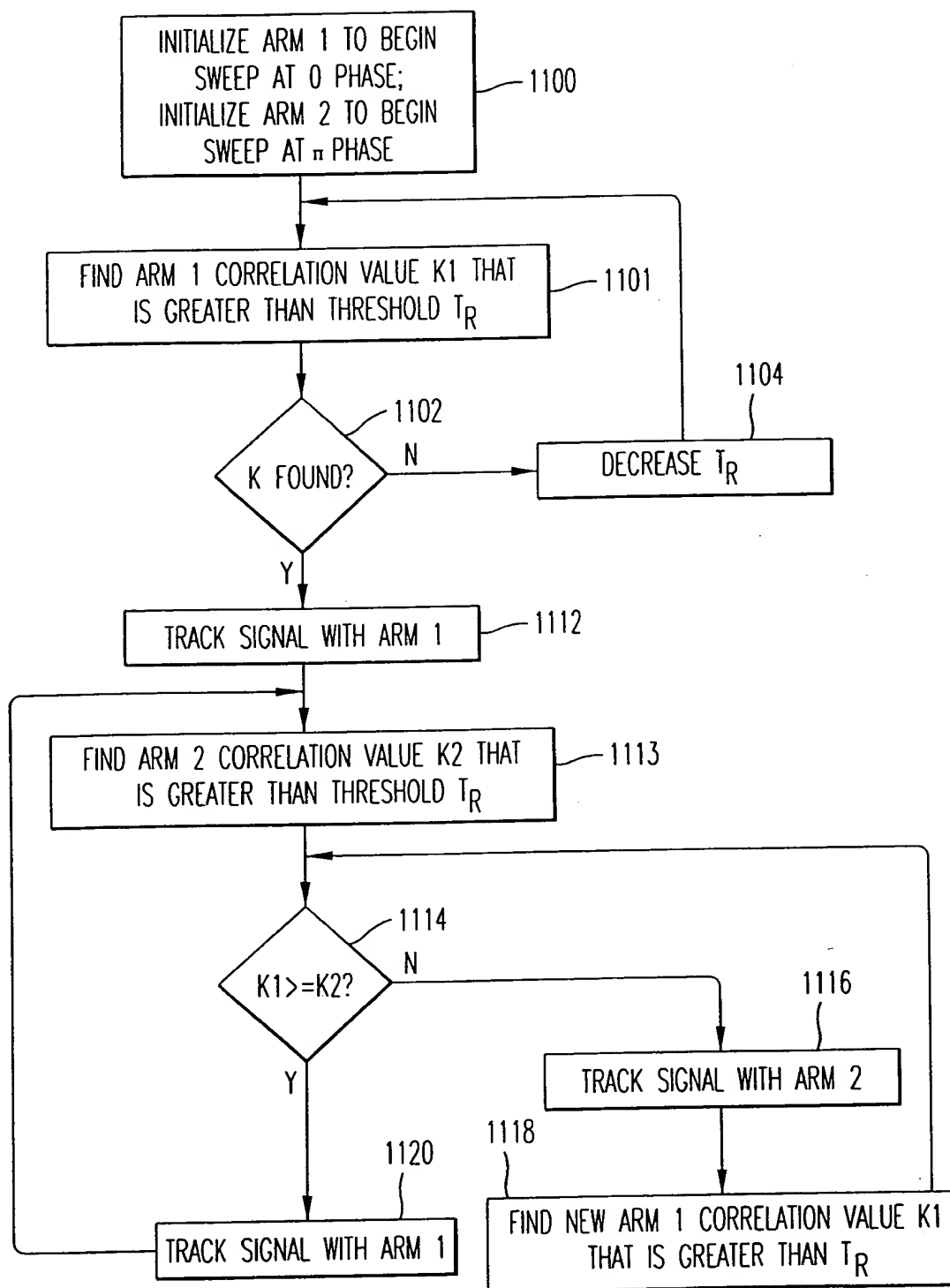


FIG. 9

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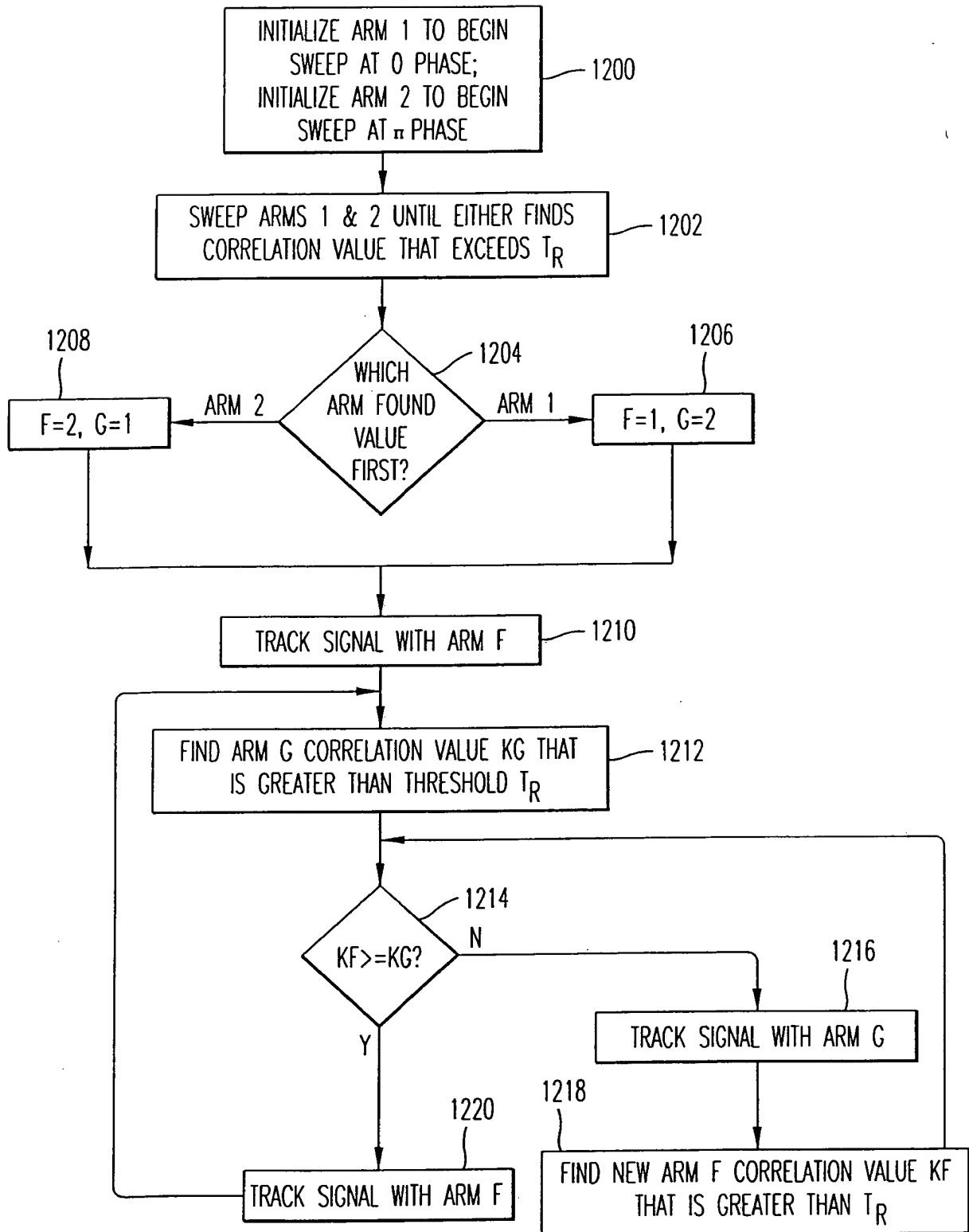


FIG. 10

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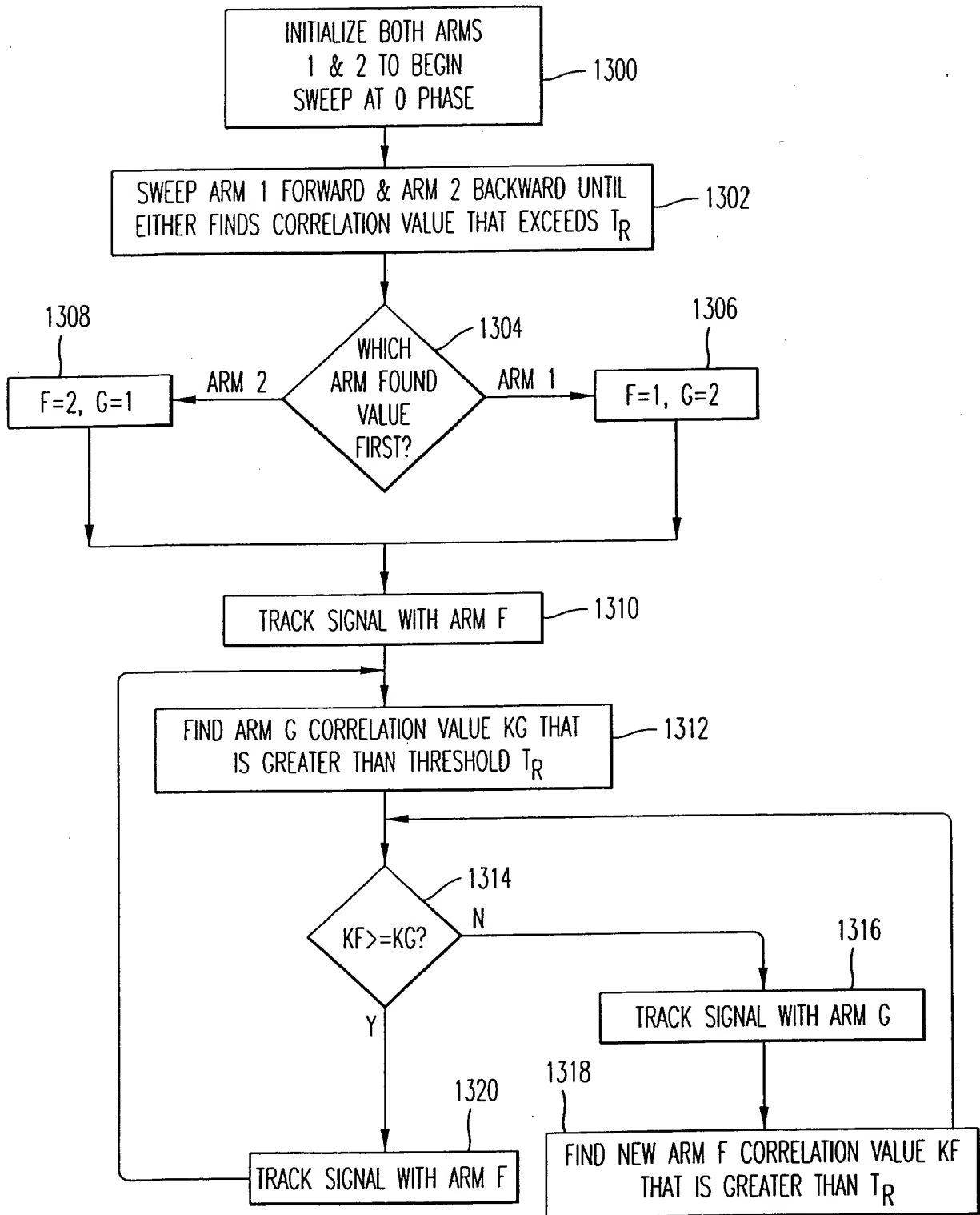


FIG. 11

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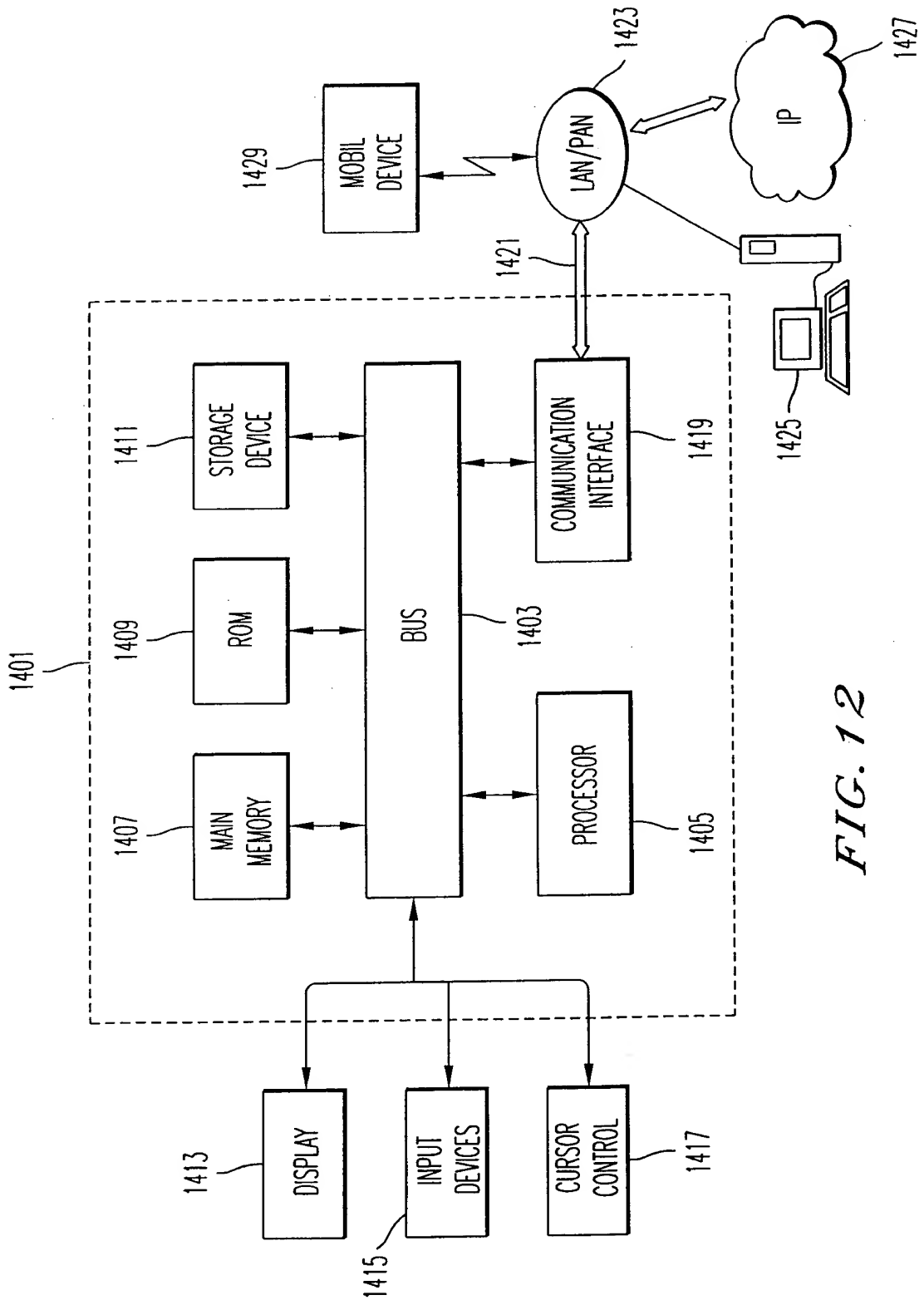


FIG. 12

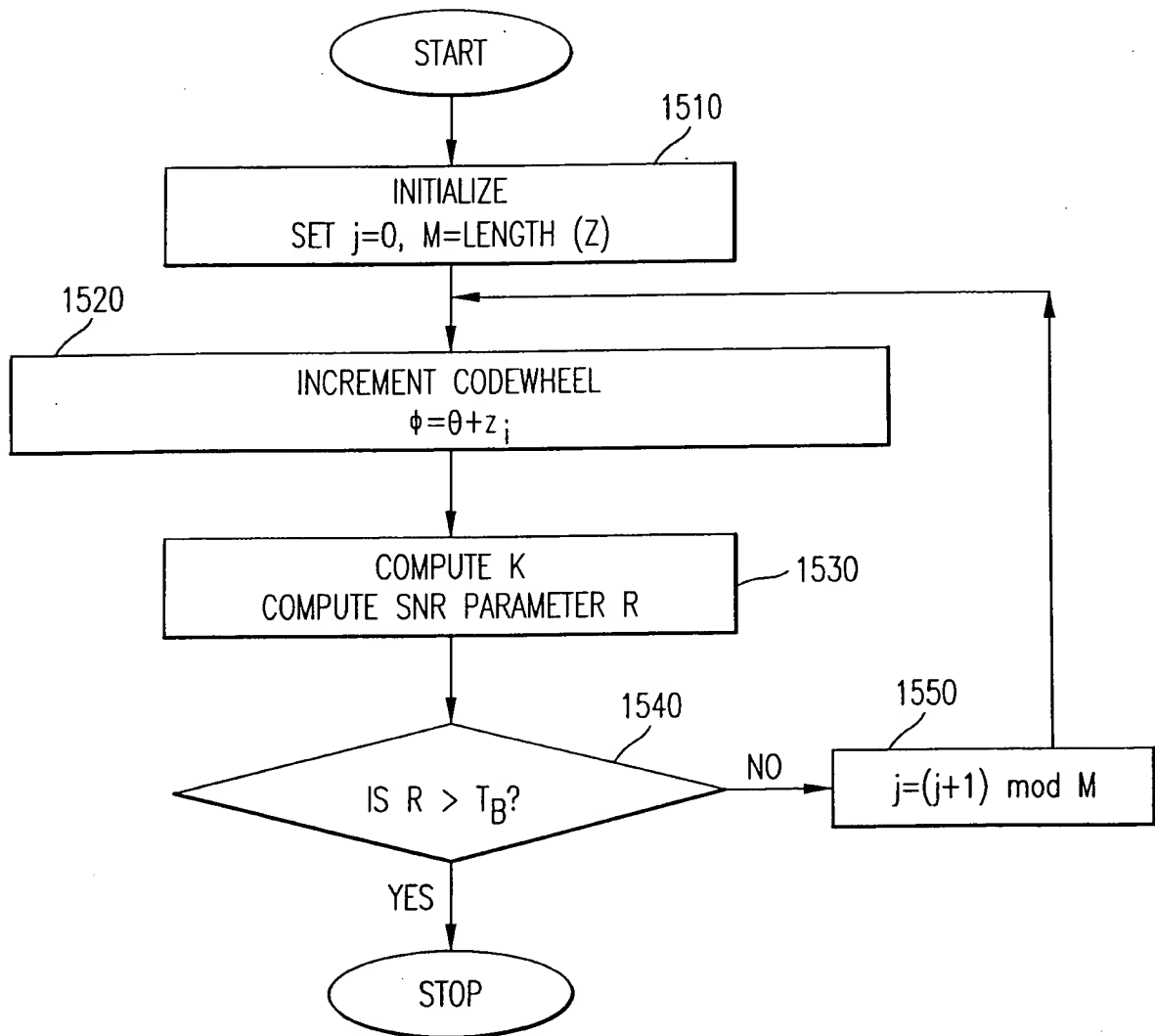
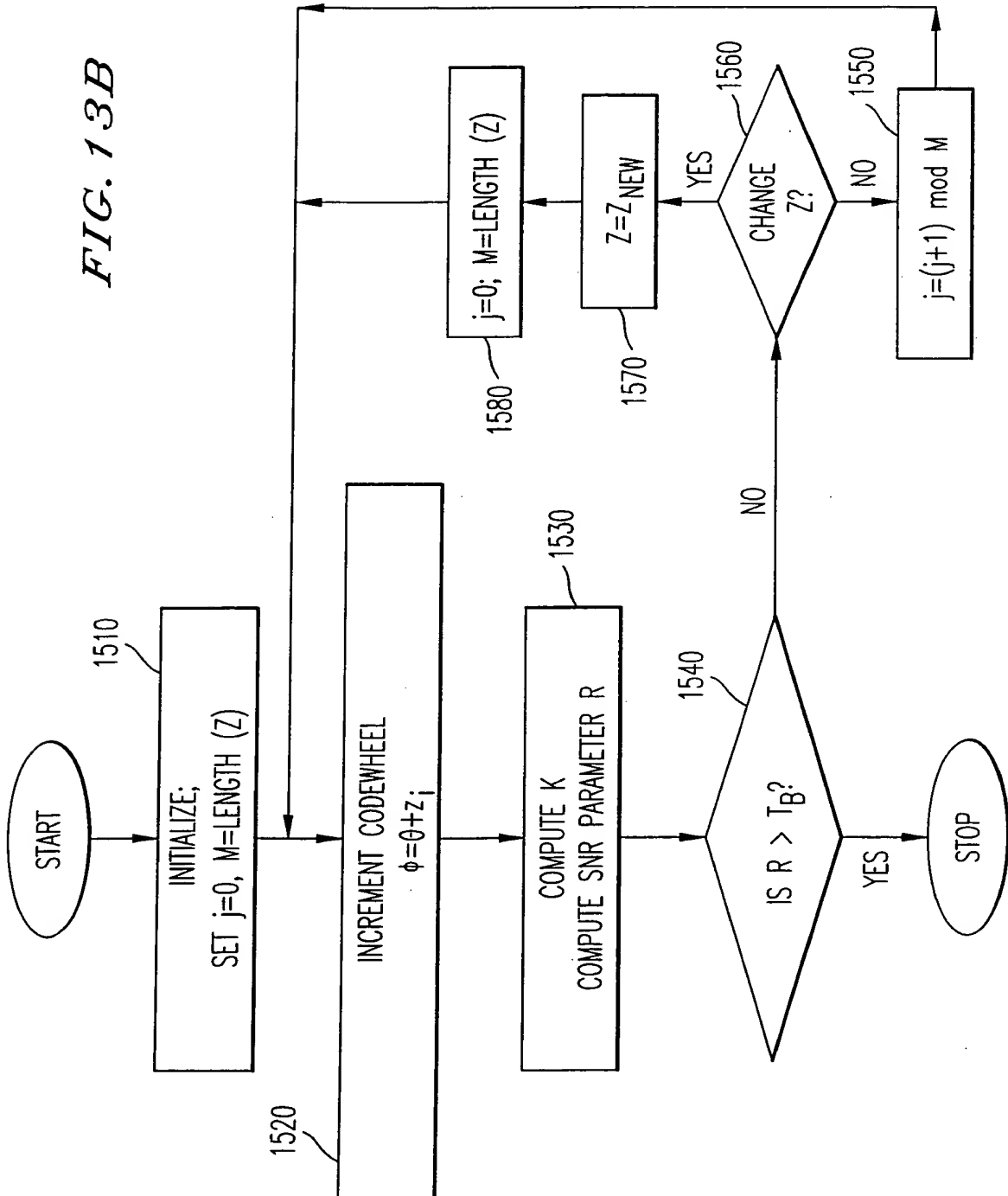
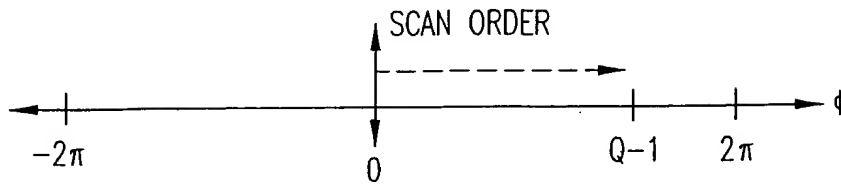
*FIG. 13A*

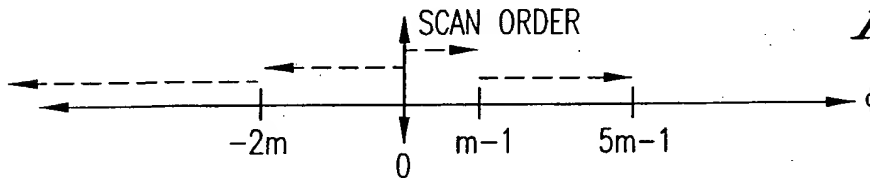
FIG. 13B



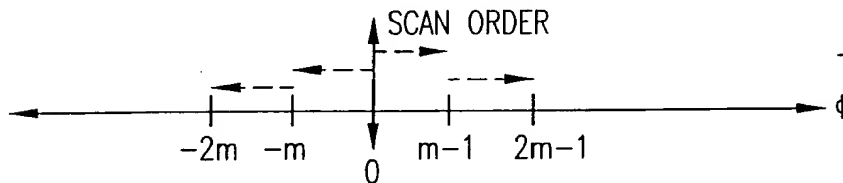
$$Z1 = \{0, n, 2n, 3n, \dots, Q-3, Q-2, Q-1\}.$$

*FIG. 14A*

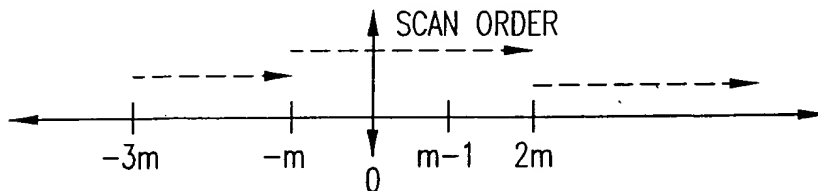
$$Z2 \text{ (FIRST EXAMPLE)} = n^* \{ [0, m-1], [-1, -2m], [m, 5m-1], [-2m-1, -10m], \dots, (Q-1)/n \}.$$

*FIG. 14B*

$$Z2 \text{ (SECOND EXAMPLE)} = \{0, n, 2n, \dots, (m-1)^*n, -n, -2n, \dots, -m^*n, m^*n, (m+1)^*n, (m+2)^*n, \dots, (Q-1)\}.$$

*FIG. 14C*

$$Z2 \text{ (THIRD EXAMPLE)} = \{-m^*n, (-m+1)^*n, (-m+2)^*n, \dots, -n, 0, n, \dots, m^*n, (m+1)^*n, (m+2)^*n, \dots, 2m^*n, \\ (-3m)^*n, (-3m+1)^*n, (-3m+2)^*n, \dots, (-m-1)^*n, (2m+1)^*n, (2m+2)^*n, \dots, (Q-1)\}.$$

*FIG. 14D*

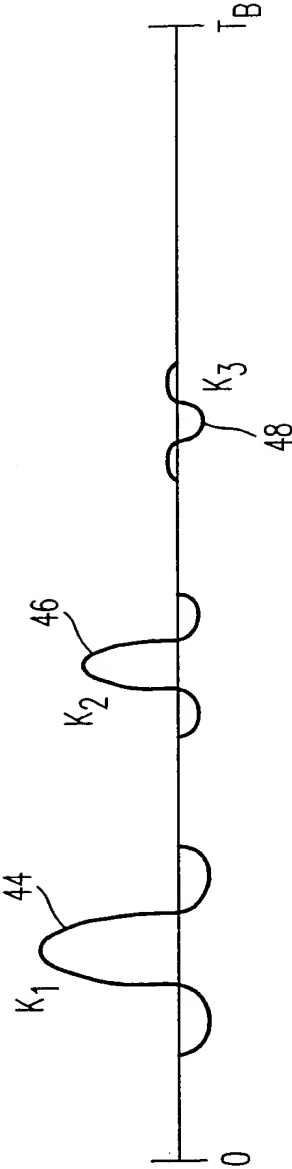
WHERE FOR FIGS. 14A, 14B, 14C, AND 14D:

$Q$  = TOTAL NUMBER OF CODEWHEEL INCREMENTS IN EACH CODEWHEEL SPIN. THE MAXIMUM CODEWHEEL SPIN IS A COMPLETE ( $2\pi$ ) CODEWHEEL SPIN, BUT OTHER CODEWHEEL SPINS ARE AVAILABLE;

$n$  = AN ARBITRARY LOCAL PARAMETER THAT CONTROLS HOW FAST THE CODE WHEEL SPINS DEPENDING ON THE TIME INCREMENT STEP SIZE; AND

$m$  = A NUMBER OF INCREMENTS LESS THAN THE TOTAL NUMBER OF INCREMENTS.

FIG. 15



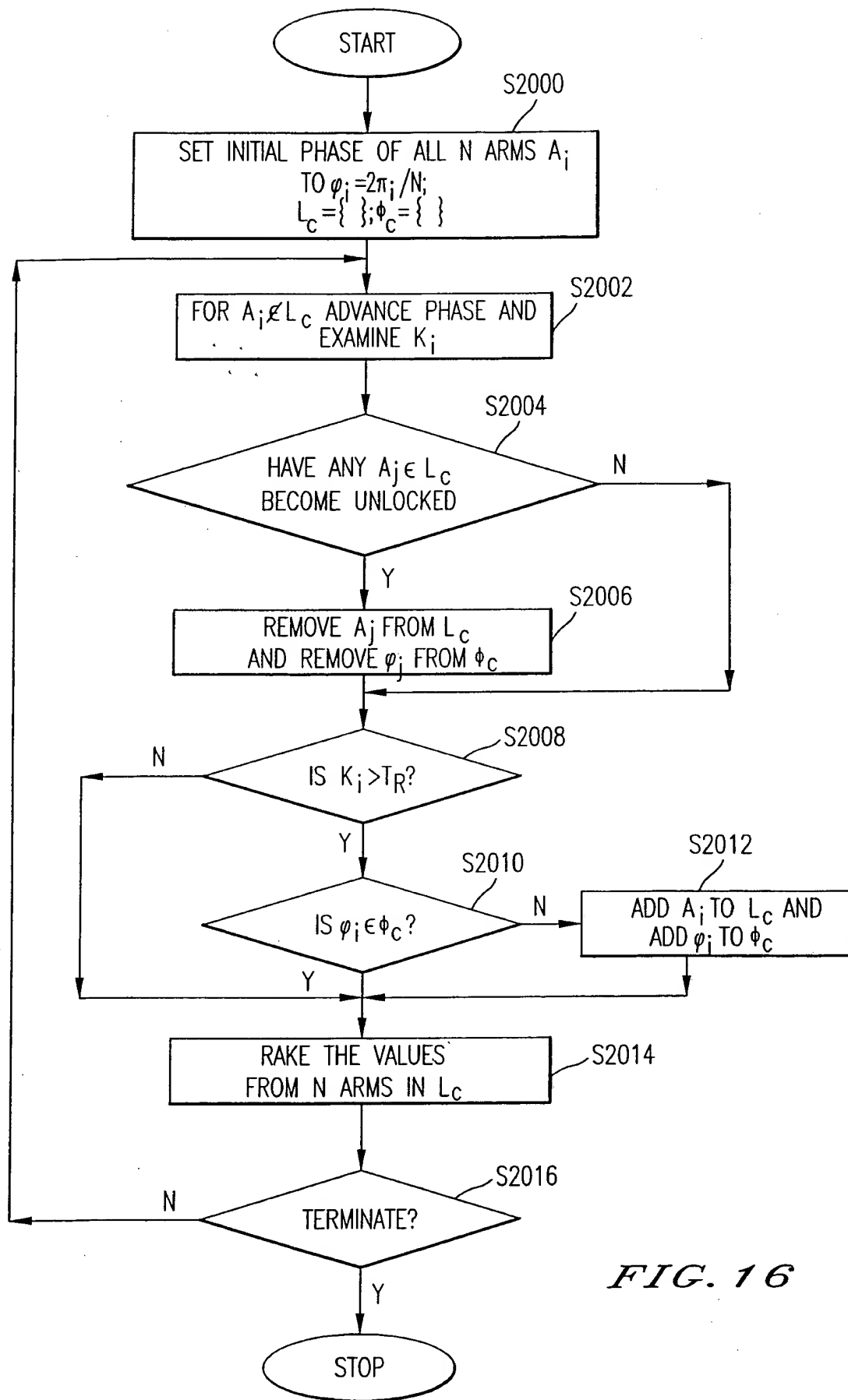
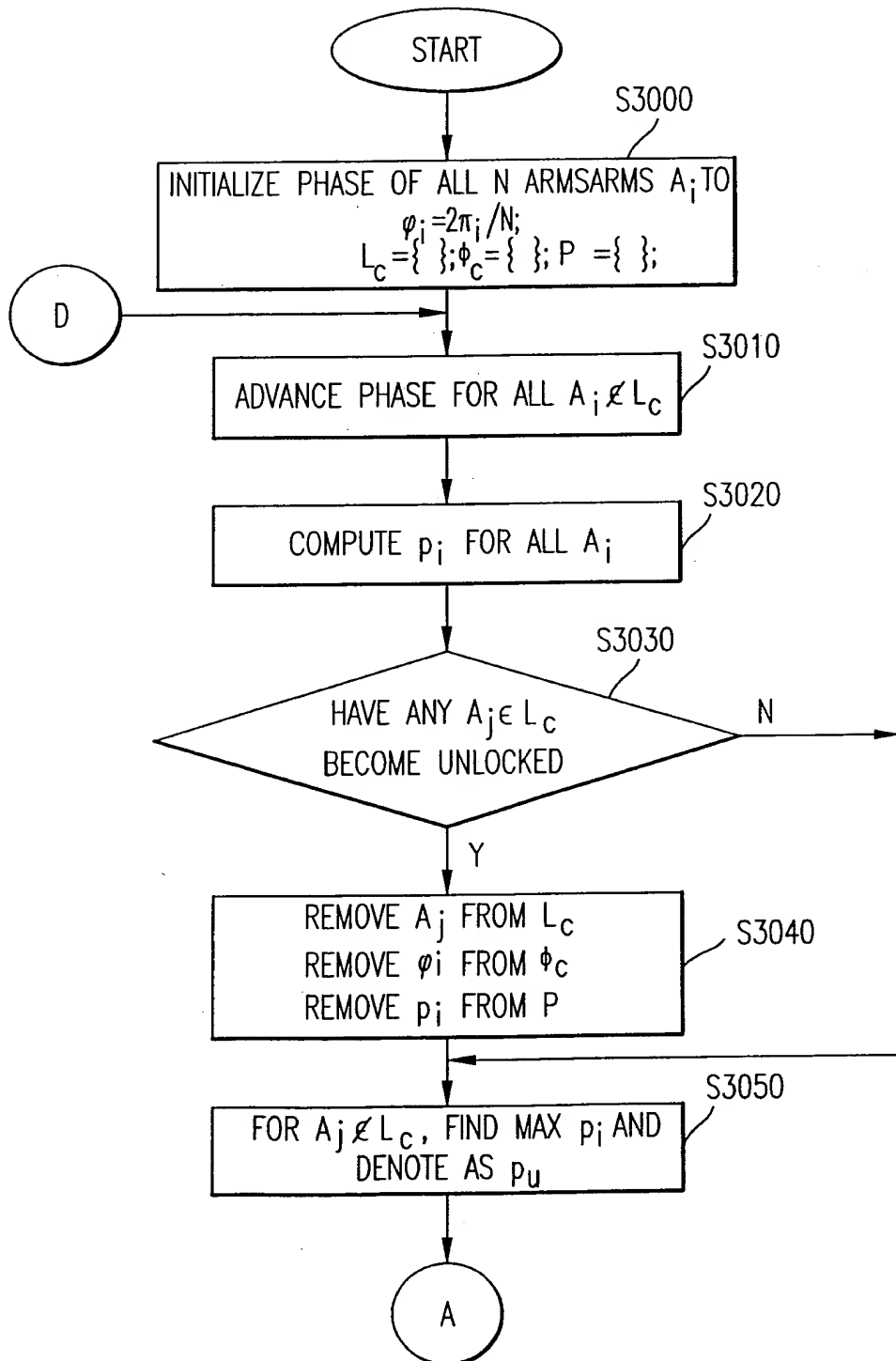
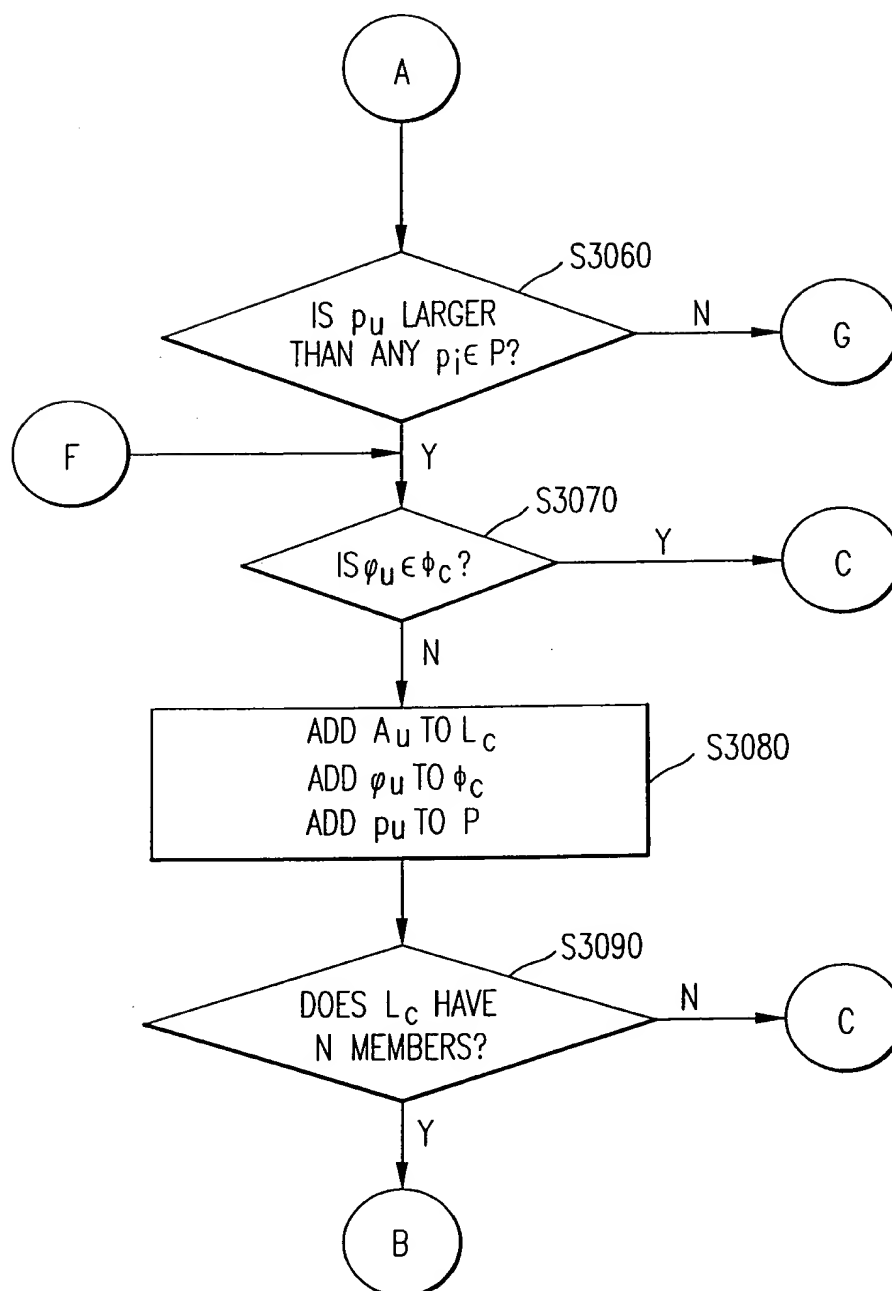
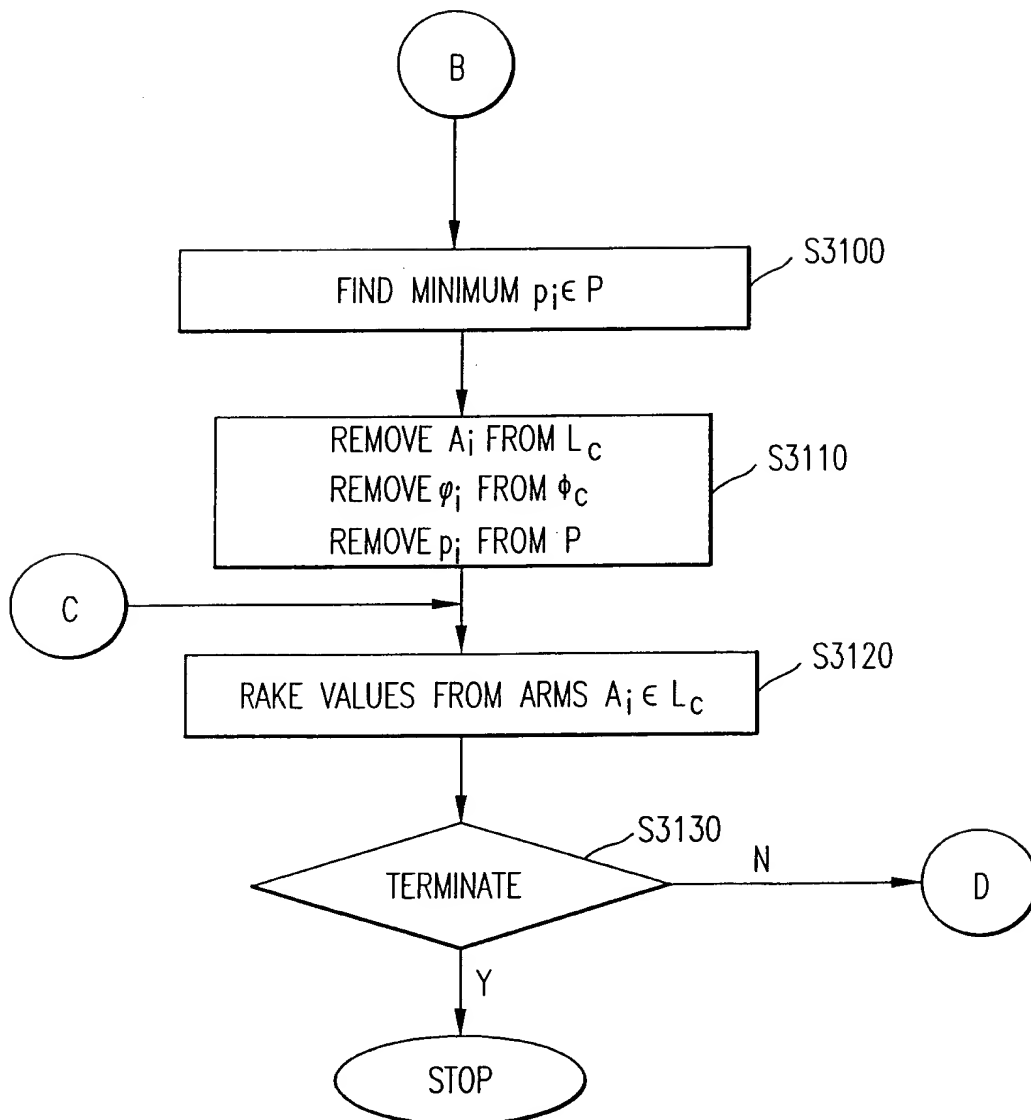


FIG. 16

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**FIG. 17A**

*FIG. 17B*

*FIG. 17C*

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*FIG. 17D*